On the Role of Burst Buffers in Leadership-Class Storage Systems

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What have we done?

- CODES: Enabling Co-Design of Multi-Layer Exascale Storage Architectures (RPI and ANL)
- Goal: apply simulation to the understanding and design of complex HPC storage system.
- We modeled a leadership class storage system[1].
	- Argonne's Blue Gene/P
	- Simulate 128K way parallelism
	- Includes a file system model: PVFS
- Burst Buffer model and study is based on BG/P model.

 [1] Modeling a Leadership-scale Storage System, N Liu, C Carothers, J Cope, P Carns, R Ross, A Crume, C Maltzahn 9th International Conference on Parallel Processing and Applied Mathematics 2011 (PPAM 2011)

Why do we need burst buffer?

- Modern HPC storage systems are designed to absorb peak I/O burst resulting in bandwidth waste.
- This storage system designs cannot keep pace with the growing data demands as supercomputers evolve to the era of exascale.

e.g. statistics from ALCF Intrepid Blue Gene/P system shows that 98.8% of the time the I/O system is at 33% bandwidth capacity or less, and 69.6% of the time the system is at 5% bandwidth capacity or less.

Aggregate I/O throughput over one-minute intervals on ALCF BG/P [2]

[2] Understanding and improving computational science storage access through continuous characterization Philip Carns, Kevin Harms, William Allcock, Charles Bacon, Samuel Lang, Robert Latham, Robert Rossl

Simulated System: IBM Blue Gene/P

Incorporating Burst Buffers on Edge of System

•We propose augmenting existing I/O node designs with a tier of solid-state disk (SSD) burst buffers.

Tools: Discrete Event Simulation

- Discrete event simulation: computer model for a system where changes in the state of the system occur at *discrete* points in simulation time.
- Fundamental concepts: system state (state variables) state transitions (events)
- A DES computation can be viewed as a sequence of event computations, with each event computation is assigned a (simulation time) time stamp
- Each event computation can modify state variables schedule new events

Why PDES?

Why Parallel Discrete-Event Simulation (PDES)?

- Large-scale systems are difficult to understand
- Analytical models are often constrained

Parallel DES simulation offers:

- Dramatically shrink model's execution-time
- Prediction of future "what-if" systems performance
- Potential for real-time decision support
	- Minutes instead of days
	- Analysis can be done right away
- Example models: national air space (NAS), ISP backbone(s), distributed content caches, next generation supercomputer systems.

ROSS: Parallel Discrete Event Simulator

- Developed in ANSI C, API is simple and lean.
- Using Jefferson's Time Warp event scheduling mechanism.
- Reverse computation.
- Global virtual time algorithm exploits IBM Blue Gene's fast barrier and collective networks.

Blue Gene/P: Time Warp Scalability

• ROSS main page:

isselaer

http://odin.cs.rpi.edu/ross/index.php/Main_Page

Write Request Event-Driven Model

Snapshot of the PVFS Write Model

Rensselaer

Burst Buffer PDES Model

Rensselaer

Study of Bursty Applications

- Argonne's Blue Gene/P system host many scientific applications.
- We quantify the I/O behavior by analyzing one month of production I/O activity from December 2011 using Darshan.
- Darshan captures application-level access pattern information with per process and per file granularity. (lightweight I/O characterization tool)

TABLE I: Top four write-intensive jobs on Intrepid, December 2011

Burst Buffer Model Parameters

TABLE II: Summary of relevant SSD device parameters and technology available as of January 2012

Burst buffer latency model:

$$
T = \frac{L_{data}}{B_{BB}} + T_{BB}
$$

Single I/O Workload Case

- Use IOR benchmark (consecutive 4MiB write requests)
- Capture write time, excludes open/close time
- Full storage system uses 128 file servers
- Half storage system uses 64 file servers

Simulated performance of IOR for various storage system and burst buffer configurations

Mixed Workload: Application View

PlasmaPhysics: 2 large (256 MiB) write with 2-hour interval. (32K processes) AstroPhysics: 3 small write followed by 1 large write, repeat 11 times. (64K processes) Turbulence1: 220 small write. (32K processes)

Full storage system with burst buffer disabled. Jobs execution time = 5.5 hours

Full storage system with burst buffer enabled.

Jobs execution time = 4.4 hours

Mixed Workload: Server View

ensselaer

Full storage system with burst buffer disabled.

Full storage system with burst buffer enabled.

Application View vs. Server View

ensselaer

Full storage system with burst buffer enabled. (Application View)

Jobs execution time = 4.4 hours

Full storage system with burst buffer enabled. (Server View)

Full Storage vs. Half Storage: Application View

Full storage system with burst buffer disabled. Jobs execution time = 5.5 hours

Half storage system with burst buffer enabled. Jobs execution time = 4.4 hours

Conclusions

- Burst buffers have been proposed as a way to meet peak I/O rates with lower performance external storage.
- We've tried to better quantify the benefits of this approach in this work.
- Bursts from applications today are of modest size, as measured on our system, allowing use of limited size buffers.
- In the context of the BG/P architecture, buffers integrated into I/O nodes could provide a measurable improvement in application time to solution while simultaneously enabling the deployment of a less capable external I/O system.

Future Work

- Investigate the use of burst buffer (in-system storage) on different tiers of the storage system
- Enable the use of simulator framework to future system architecture
- Understand complex system components and facilitate the design through simulation

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- Thanks everyone here today!
- Questions?

